

## 一、简答题

416 工程流体力学答案

1. 某点的流速: ① 风速仪, ② 皮托管+U形管. 皮托管对准来流方向.

阻力  $= H_2 - H_1$ ,  $H$  为总水头, 即同时测量 1、2 两个断面的总水头.

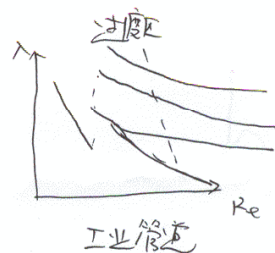
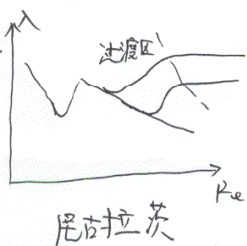
2. ① 如将突扩(缩)管改为渐扩(缩)管.

② 增大弯管的曲率半径.

③ 管道入口改为流线形

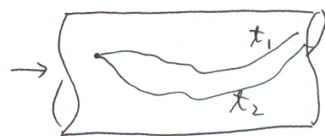
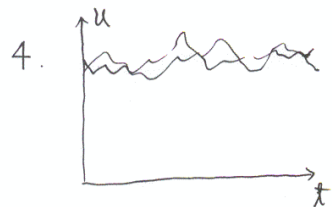
④ 三通管的角度合理.

3. 不能



由上图可以看出, 尼古拉茨速度区入的变化趋势完全不同于

工业管道.



- ① 随机性: 任意两次的速度测量结果不重复. 过一点不同时间的轨迹线不重合.

② 速度线不可用某一函数来表述，轨迹线不可用某一函数来表述

③ 时均速度为常数 (恒定流动条件下)。

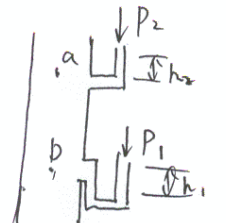
5. 三种：前弯、后弯、径向。

前弯叶片对流体做功能力最大，后弯最小。

……的效率最低，后弯最高

……的噪声最大，……小。

二.



$$P_b = P_a + \rho_G H \Rightarrow P_b - P_a = \rho_G H$$

$$\begin{cases} P_b = P_1 + h_1 \rho_{fl} - h_1 \rho_G \\ P_a = P_2 + h_2 \rho_{fl} - h_2 \rho_G \end{cases}$$

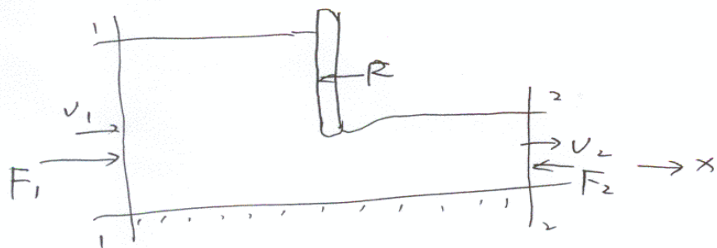
$$\Rightarrow P_b - P_a = P_1 - P_2 + h_1 \rho_{fl} - h_1 \rho_G - h_2 \rho_{fl} + h_2 \rho_G$$

$$\Rightarrow \rho_G H = P_1 - P_2 + h_1 \rho_{fl} - h_1 \rho_G - h_2 \rho_{fl} + h_2 \rho_G$$

$$\text{又 } P_1 - P_2 = \rho_A H$$

$$\Rightarrow h_2 (\rho_{fl} - \rho_G) = \rho_A H + h_1 (\rho_{fl} - \rho_G) - H \rho_G$$

$$h_2 = h_1 + \frac{\rho_A - \rho_G}{\rho_{fl} - \rho_G} H = 125.3 \text{ mm H}_2\text{O}.$$



$$z_1 + \frac{P_1}{\rho} + \frac{\alpha_1 V_1^2}{2g} = z_2 + \frac{P_2}{\rho} + \frac{\alpha_2 V_2^2}{2g} + h \rightarrow 0$$

$$H + \frac{V_1^2}{2g} = h + \frac{V_2^2}{2g} \quad (1)$$

$$\Rightarrow H \cdot 2 \cdot V_1 = h \cdot 2 \cdot V_2 \Rightarrow V_2 = 2V_1 \quad (2)$$

$$\Rightarrow (1), (2), (3) \quad \begin{cases} V_1 = 2.557 \text{ m/s} \\ V_2 = 5.114 \text{ m/s} \end{cases}$$

由动量方程:

$$\sum F_x = \rho Q (\alpha_2 V_2 - \alpha_1 V_1)$$

$$F_1 - F_2 - R = \rho 2h \cdot V_2 (V_2 - V_1)$$

$$R = F_1 - F_2 - 2h \rho V_2 \cdot V_1 \quad (3)$$

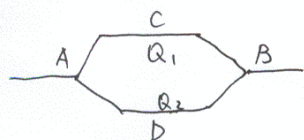
$$F_1 = P_1 \cdot A_1 = \rho \cdot \frac{H}{2} \cdot H \cdot 2 = \rho H^2$$

$$F_2 = P_2 \cdot A_2 = \rho \cdot \frac{h}{2} \cdot h \cdot 2 = \rho h^2$$

代入 (3), (5) 得:

$$\begin{aligned} R &= \rho (H^2 - h^2) - 2h \rho V_2 V_1 \\ &= 9807 \times 3 - 2 \times 1 \times 1000 \times 2.557 \times 5.114 \\ &= 3.268 \times 10^3 \text{ N} \end{aligned}$$

14.



$$h_{fACB} = \lambda \frac{51}{d_1} \cdot \frac{V_1^2}{2g} = 60 \cdot \frac{V_1^2}{2g}$$

$$h_{fADB} = \lambda \frac{52}{d_2} \cdot \frac{V_2^2}{2g} = 36 \frac{V_2^2}{2g}$$

$$\Rightarrow h_{fACB} = h_{fADB} \quad \text{即}$$

$$60 V_1^2 = 36 V_2^2 \Rightarrow V_1 = 0.7746 V_2 \quad (1)$$

$$\Rightarrow \frac{\pi}{4} d_1^2 V_1 + \frac{\pi}{4} d_2^2 V_2 = Q \quad (2)$$

$$\text{即} \begin{cases} V_2 = 1.4357 \text{ m/s} \\ V_1 = 1.1121 \text{ m/s} \end{cases}$$

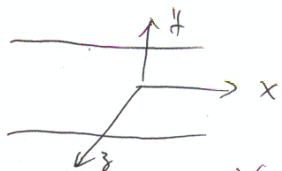
$$Q_1 = \frac{\pi}{4} d_1^2 V_1 = 0.035 \text{ m}^3/\text{s}$$

$$Q_2 = \frac{\pi}{4} d_2^2 V_2 = 0.045 \text{ m}^3/\text{s}$$

$$h_f = \lambda \frac{51}{d_1} \cdot \frac{V_1^2}{2g} = 3.786 \text{ m}$$

15.  $u_y = u_z = 0$

$$u_x = u_x(y)$$



$$\frac{\partial u_x}{\partial x} + u_x \frac{\partial u_x}{\partial x} + u_y \frac{\partial u_x}{\partial y} + u_z \frac{\partial u_x}{\partial z} = g_x - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left( \frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial y^2} + \frac{\partial^2 u_x}{\partial z^2} \right)$$

$$\frac{1}{\rho} \frac{\partial p}{\partial x} = \frac{d^2 u_x}{dy^2} \quad \frac{du_x}{dy} = \frac{1}{\rho} \frac{\partial p}{\partial x} y + C$$

$$\text{即} \left. \frac{du_x}{dy} \right|_{y=0} = 0 \quad \text{即} \quad C = 0$$

$$\frac{du_x}{dy} = \frac{1}{\rho} \frac{\partial p}{\partial x} y \quad u_x = \frac{1}{2\rho} \frac{\partial p}{\partial x} y^2 + C_1$$

$$\text{由 } u_x|_{y=h} = 0 \text{ 设 } C_1 = -\frac{1}{2g} \frac{\partial \psi}{\partial x} h^2$$

$$\therefore u_x = \frac{1}{2g} \frac{\partial \psi}{\partial x} (y^2 - h^2)$$

$$\text{由 } Re_m = Re_p$$

$$\begin{aligned} \frac{l_m u_m}{\nu_m} &= \frac{l_p u_p}{\nu_p} & l_m &= \frac{u_p}{u_m} \cdot \frac{\nu_m}{\nu_p} \cdot l_p \\ & & &= \frac{0.3}{18} \cdot \frac{15.2 \times 10^{-6}}{1.007 \times 10^{-6}} \times 1.5 \\ & & &= 3.77 \text{ m} \end{aligned}$$

$$b_m = \frac{3}{18} \cdot \frac{15.2 \times 10^{-6}}{1.007 \times 10^{-6}} \times 0.3 = 0.75 \text{ m}$$

$$\text{由 } \frac{F_m}{\rho_m l_m^2 u_m^2} = \frac{F_p}{\rho_p l_p^2 u_p^2}$$

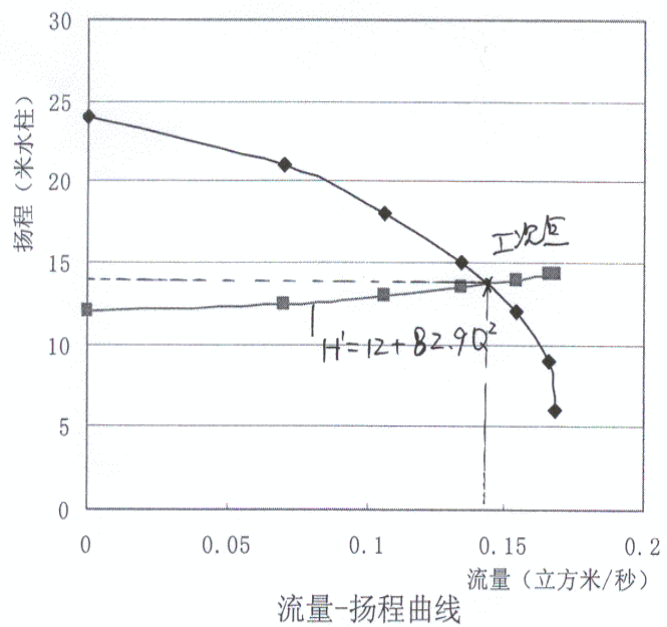
$$F_m = \frac{\rho_m}{\rho_p} \frac{l_m^2}{l_p^2} \frac{u_m^2}{u_p^2} F_p = \frac{1.227}{1.007} \cdot \left(\frac{3.77}{1.5}\right)^2 \times \left(\frac{18}{3}\right)^2 \cdot 14 = 3.9 \text{ N}$$

$$\rho_m = \frac{\rho_m}{R_m T_m} = 1.227 \text{ kg/m}^3$$

$$\text{由 } \underbrace{z_1}_0 + \underbrace{\frac{p_1}{\rho}}_0 + \underbrace{\frac{\alpha V_1^2}{2g}}_0 + H' = \underbrace{z_2}_H + \underbrace{\frac{p_2}{\rho}}_0 + \underbrace{\frac{\alpha V_2^2}{2g}}_0 + h$$

$$H' = H + h$$

$$h = \lambda \frac{l}{d} \frac{V^2}{2g} + \xi \frac{V^2}{2g} = \left( \lambda \frac{l}{d} + \xi \right) \frac{Q^2}{\left( \frac{\pi}{4} d^2 \right)^2 \cdot 2g}$$



工况点:  
 $Q = 0.147 \text{ m}^3/\text{s}$   
 $H = 13.44 \text{ m}$   
 $\eta = 78\%$

