

424 微机原理

一、

1. FFFF0H; 2. 基址寻址, 数据段; 3. 30000H+0020H=30020H;
4. SS=1234H, SP=00FEH, (SP)=78H, (SP+1)=56H; 5. 例 OUT 40H, AL 或 OUT DX, AL; 6. CPU 一响应中断先关中断, RET 前必须开中断 (STI), 否则无法响应下面的中断; 7. 先写某计数器的控制字, 后写初始值;
8. 保持到 CPU 对 C 口数据采样完成; 9. 不能, 因接收过程中产生错位而不能正确接收;
10. 在中断响应周期中, CPU 发第二个中断响应信号/INTA 时, CPU 读取数据线上的中断类型号 n。

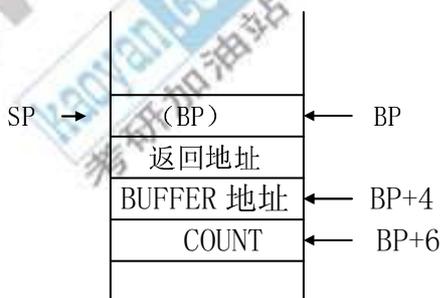
二、

1. DS: 0000H	F0H	STR1
0001H	FFH	
0002H	41H	STR2
0003H	01H	
0004H	41H	
0005H	01H	
0006H	02H	STR3
0007H	00H	

2. (1) DI=0000H, 立即寻址; (2) CX=6, 立即寻址;
- (3) CX=0008H, 基址+变址寻址;
- (4) (SP)= 0008H, 寄存器寻址; DI=0008H, SP 寄存器间接寻址;

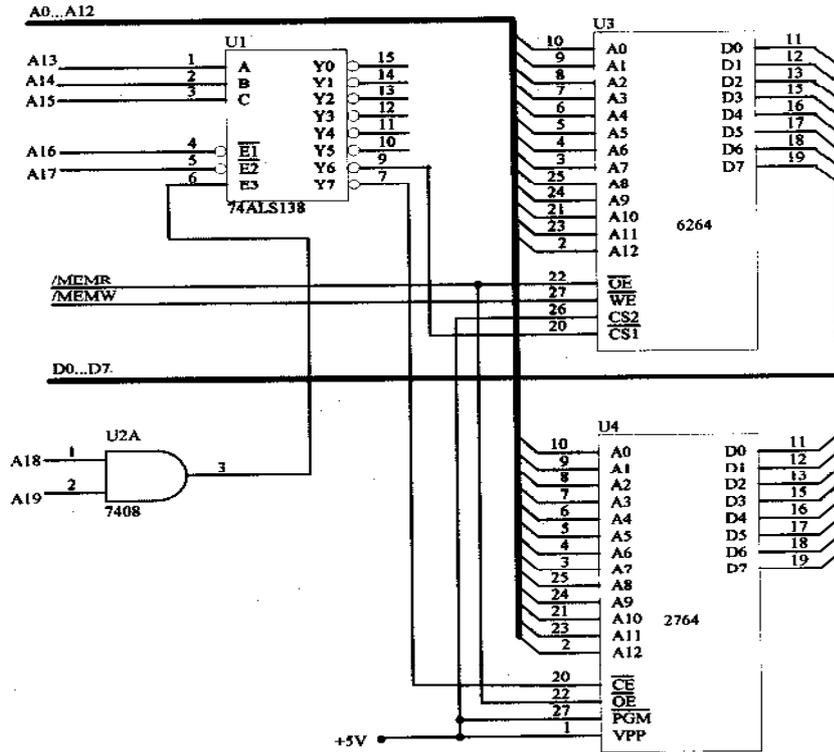
三、

1. \$=6;
- 2.



3. (BP+4)= BUFFER 偏移地址
4. ① DS, ② MAXVAL, ③ AGAIN
5. RET 4 功能: 返回偏移地址 → IP, SP=SP+2, SP=SP+4
RET 4 本程序中的目的: 指向栈底。

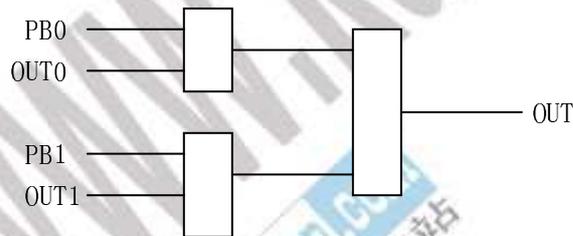
四、



五、

1. 8255:8CH-8FH, 8253:94H-97H
2. CNT0:初值=1000000/1000=1000, 控制字=00110110B=36H
 CNT1:初值=1000000/500=2000, 控制字=01110110B=76H
 CNT2:初值=10000/1=10000, 控制字=10110000B=BOH
 8255: 控制字=10000000B=80H

3.



4. 主程序:

```

MOV AL, 80H
OUT 8FH, AL
MOV AL, 36H
OUT 97H, AL
MOV AL, 76H
OUT 97H, AL
MOV AL, 0B0H
OUT 97H, AL
MOV AX, 1000
OUT 94H, AL
MOV AL, AH
    
```

```

    OUT 94H, AL
    MOV AX, 2000
    OUT 95H, AL
    MOV AL, AH
    OUT 95H, AL
    MOV AX, 1000
    OUT 96H, AL
    MOV AL, AH
    OUT 96H, AL
    MOV AL, 01H
    OUT 8DH, AL
    
```

中断程序:

```

    IN AL, 8DH
    NOT AL
    OUT 8DH, AL
    MOV AL, 20H,
    OUT 20H, AL
    STI
    IRET
    
```

六、

1. 线路控制字=00001011B=0BH, 波特率系数= $1843200 / (16 * 300) = 0180H$
2. 线路控制寄存器=1000000B 时, 3F8H、3F9H 为除数寄存器地址
3. 初始化程序:

```

    MOV DX , 3FBH; 线路控制寄存器地址
    MOV AL , 00001011H
    OUT DX , AL
    MOV AL , 80H
    OUT DX , AL
    MOV DX , 3F9H
    MOV AL , 01H
    OUT DX , AL
    MOV DX , 3F8H
    MOV AL , 80H
    OUT DX , AL
    
```

4. 主 PC 机发送程序:

```

    DATA SEGMENT
    TDATA DB '123ASFFGJFHJFJT DJ $'
    DATA ENDS
    CODE SEGMENT
        ASSUME CS: CODE
    START: MOV AX, DATA
            MOV DS, AX
            MOV SI, OFFSET TDATA
    ZJO:   MOV DX, 3FDH
    
```

```

        IN AL, DX
        TEST AL, 20H
        JZ ZJ0
        MOV DX, 3F8H
        MOV AL, [SI]
        OUT DX, AL
        CMP AL, '$'
        JZ ZJ3
        INC SI
        JMP ZJ0
    ZJ3: MOV AH, 4CH
        INT 21H
CODE ENDS
        END START
    
```

从 PC 机接收程序:

```

DATA SEGMENT
RDATA DB 120 DUP (0)
DATA ENDS
CODE SEGMENT
        ASSUME CS: CODE
START: MOV AX, DATA
        MOV DS, AX
        MOV SI, OFFSET RDATA
    ZJ0: MOV DX, 3FDH
        IN AL, DX
        TEST AL, 01H
        JZ ZJ0
        MOV DX, 3F8H
        IN AL, DX
        MOV [SI], AL
        CMP AL, '$'
        JZ ZJ3
        MOV AH, 2
        MOV DL, AL
        INT 21H
        INC SI
        JMP ZJ0
    ZJ3: MOV AH, 4CH
        INT 21H
CODE ENDS
        END START
    
```